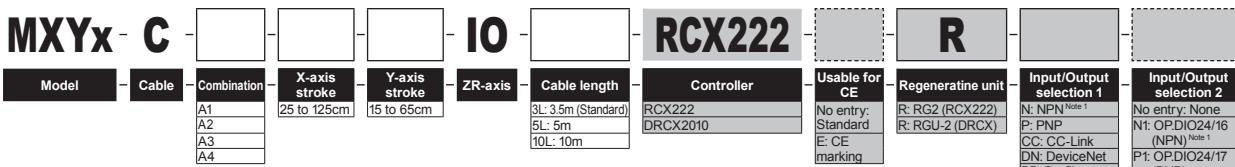


Arm type Cable carrier

Ordering method



Note 1. NPN and Ethernet cannot be selected if using CE marking.

Note 2. Available only for the master.

Note 3. Only when CC or DN or PB was selected for I/O select 1 above, EN can be selected in I/O select 2.

Specification

	X-axis	Y-axis
Axis construction ^{Note 1}	F17	F14H
AC servo motor output (W)	400	200
Repeatability ^{Note 2} (mm)	+/-0.01	+/-0.01
Drive system	Ball screw (Class C7)	Ball screw (Class C7)
Ball screw lead (Deceleration ratio) (mm)	20	20
Maximum speed (mm/sec)	1200	1200
Moving range (mm)	250 to 1250	150 to 650
Robot cable length (m)	Standard: 3.5 Option: 5.10	

Note 1. Use caution that the flame machining (installation holes, tap holes) differs from single-axis robots'.

Note 2. Positioning repeatability in one direction.

Note 3. When the X-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

Maximum payload

Y stroke (mm)	XY 2 axes
150	29
250	29
350	24
450	19
550	19
650	15

Controller

Controller	Operation method
RCX222-R	Programming / I/O point trace / Remote command / Operation using RS-232C communication
DRCX2010-R	

MXYx 2 axes / IO A1

