

Arm type
Cable carrier

Ordering method

SXYx - C

**RCX222** 

No entry: None N1: OP.DIO24/16 (NPN) Note 1 P1: OP.DIO24/17 FN: Ethernet Note 1

Note 1. NPN and Ethernet cannot be selected if using CE marking

Note 2. Available only for the master.

Note 3. Only when CC or DN or PB was selected for I/O select 1 above. EN can be selected in I/O select 2.

■ Specification		
	X-axis	Y-axis
Axis construction Note 1	F14H	F14
AC servo motor output (W)	200	100
Repeatability Note 2 (mm)	+/-0.01	+/-0.01
Drive system	Ball screw (Class C7)	Ball screw (Class C7)
Ball screw lead (Deceleration ratio) (mm)	20	20
Maximum speed Note 3 (mm/sec)	1200	1200
Moving range (mm)	150 to 1050	150 to 650
Robot cable length (m)	Standard: 3.5 Option: 5,10	

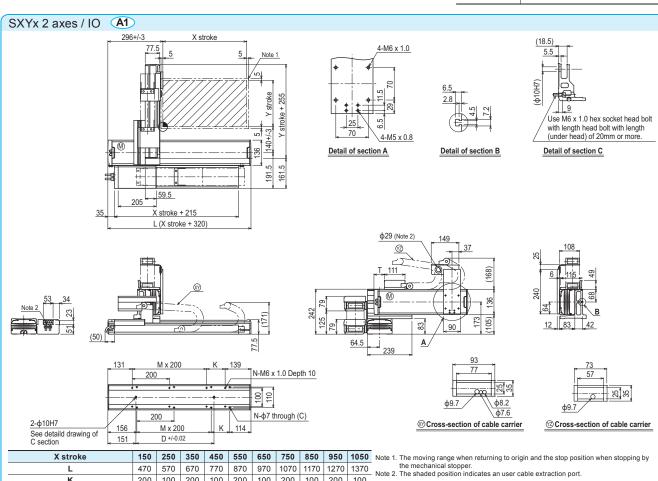
Maximum payload (kg) Y stroke (mm) XY 2 axes 

Note 1. Use caution that the flame machining (installation holes, tap holes) differs from single-axis robots'.

Note 2. Positioning repeatability in one direction.

Note 3. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

■ Controller		
Controller	Operation method	
RCX222	Programming / /O point trace / Remote command / Operation using RS-232C communication	
DRCX1005		



K D M Ν Y stroke 

Maximum speed for each stroke (mm/sec) No e3 960 780 600 540 Speed setting 80% 65% 50% 45%

 When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.