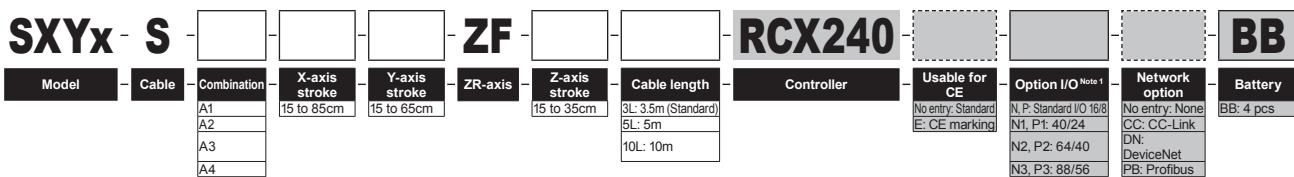


## Ordering method



Note 1. N to N4 if NPN was selected, or P to P4 if PNP was selected for the I/O board.

Note 2. Available only for the master.

## Specification

	X-axis	Y-axis	Z-axis
Axis construction <sup>Note 1</sup>	F14H	F14	F10-BK
AC servo motor output (W)	200	100	100
Repeatability <sup>Note 2</sup> (mm)	+/-0.01	+/-0.01	+/-0.01
Drive system	Ball screw (Class C7)	Ball screw (Class C7)	Ball screw (Class C7)
Ball screw lead (Deceleration ratio) (mm)	20	20	10
Maximum speed <sup>Note 3</sup> (mm/sec)	1200	1200	600
Moving range (mm)	150 to 850	150 to 650	150 to 350
Robot cable length (m)	Standard: 3.5 Option: 5,10		

Note 1. Use caution that the flame machining (installation holes, tap holes) differs from single-axis robots'.

Note 2. Positioning repeatability in one direction.

Note 3. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

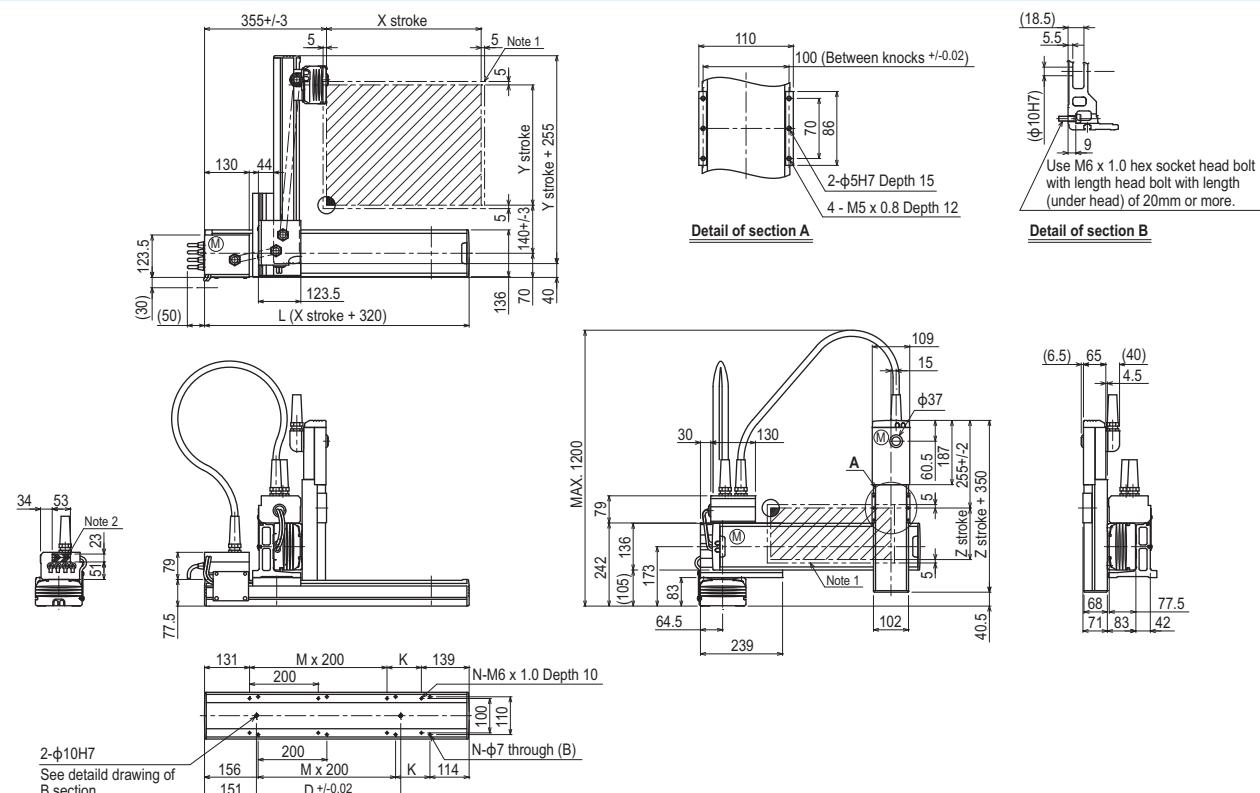
## Maximum payload

Y stroke (mm)	Z stroke (mm)		
	150	250	350
150	10	10	10
250	10	10	9
350	9	8	7
450	7	6	5
550	5	4	3
650	3	2	1

## Controller

Controller	Operation method
RCX240	Programming / I/O point trace / Remote command / Operation using RS-232C communication

## SXYx 3 axes / ZF A1



X stroke	150	250	350	450	550	650	750	850
L	470	570	670	770	870	970	1070	1170
K	200	100	200	100	200	100	200	100
D	240	240	420	420	600	600	780	960
M	0	1	1	2	2	3	3	4
N	4	6	6	8	8	10	10	12

Y stroke	150	250	350	450	550	650
Z stroke	150	250	350			

Maximum speed for each stroke (mm/sec) <sup>Note 3</sup>	X-axis	1200	960	780
Speed setting		-	80%	65%

Note 1. The moving range when returning to origin and the stop position when stopping by the mechanical stopper.

Note 2. The shaded position indicates an user cable extraction port.

Note 3. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.

APPLICATION	Compact single-axis robots
TRANSEROV	Single-axis robots
FLIP-X	Linear motor single-axis robots
PHASER	Cartesian robots
YK-XG	SCARA robots
YP-X	Pick & place robots
CLEAN	CLEAN
CONTROLLER	CONTROLLER
INFORMATION	INFORMATION
Arm type	Arm type
Gantry type	Gantry type
Moving arm type	Moving arm type
Pole type	Pole type
XZ type	XZ type