APPLICATION

TRANSERVO
Compact single-axis robots

FLIP-X
Single-axis robots

PHASER
Linear motor single-axis robots

XY-X
Cartesian robots

YK-XG
SCARA robots

YP-X
Pick & place robots

CLEAN

CONTROLLER

INFORMATION

Arm type

Gantry type

Moving arm type

Pole type

XZ type

SXYx

3 axes / ZF

● Arm type   ● Cable carrier   ● Z-axis: clamped base / moving table type (100W)

■ Ordering method

SXYx - **C** [ ] [ ] [ ] **ZF** [ ] [ ] **RCX240** [ ] [ ] [ ] **BB**

Model	Cable	Combination	X-axis stroke	Y-axis stroke	ZR-axis	Z-axis stroke	Cable length	Controller	Usable for CE	Option I/O Note 1	Network option	Battery
		A1 A2 A3 A4	15 to 105cm	15 to 65cm		15 to 35cm	3L: 3.5m (Standard) 5L: 5m 10L: 10m		No entry: Standard E: CE marking	N, P: Standard I/O 16/8 N1, P1: 40/24 N2, P2: 64/40 N3, P3: 88/56 N4, P4: 112/72	No entry: None CC: CC-Link DN: DeviceNet PB: Profibus EN: Ethernet YC: YC-Link Note 2	BB: 4 pcs

Note 1. N to N4 if NPN was selected, or P to P4 if PNP was selected for the I/O board.
Note 2. Available only for the master.

■ Specification

	X-axis	Y-axis	Z-axis
Axis construction Note 1	F14H	F14	F10-BK
AC servo motor output (W)	200	100	100
Repeatability Note 2 (mm)	+/-0.01	+/-0 01	+/-0.01
Drive system	Ball screw (Class C7)	Ball screw (Class C7)	Ball screw (Class C7)
Ball screw lead (Deceleration ratio) (mm)	20	20	10
Maximum speed Note 3 (mm/sec)	1200	1200	600
Moving range (mm)	150 to 1050	150 to 650	150 to 350
Robot cable length (m)	Standard: 3.5 Option: 5,10		

Note 1. Use caution that the flame machining (installation holes, tap holes) differs from single-axis robots'.
Note 2. Positioning repeatability in one direction.
Note 3. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

■ Maximum payload (kg)

	Z stroke (mm)		
Y stroke (mm)	150	250	350
150	10	10	10
250	10	10	9
350	9	8	7
450	7	6	5
550	5	4	3
650	3	2	1

■ Controller

Controller	Operation method
RCX240	Programming / /O point trace / Remote command / Operation using RS-232C communication

SXYx 3 axes / ZF　A1

Detail of section A
4 - M5 x 0.8 Depth 12
2-φ5H7 Depth 15

Detail of section B

Detail of section C
Use M6 x 1.0 hex socket head bolt with length head bolt with length (under head) of 20mm or more

⊗Ⓨ Cross-section of cable carrier

⊗Ⓩ Cross-section of cable carrier

2-φ10H7
See detaild drawing of C section

N-M6 x 1.0 Depth 10
N-φ7 through (C)

X stroke	150	250	350	450	550	650	750	850	950	1050
L	470	570	670	770	870	970	1070	1170	1270	1370
K	200	100	200	100	200	100	200	100	200	100
D	240	240	420	420	600	600	780	960	960	1140
M	0	1	1	2	2	3	3	4	4	5
N	4	6	6	8	8	10	10	12	12	14

Y stroke	150	250	350	450	550	650
T	55	110	165	220	275	330

Z stroke	150	250	350

Maximum speed for each stroke (mm/sec) No e3	X-axis	1200			960	780	600	540
	Speed setting	–			80%	65%	50%	45%

Note 1. The moving range when returning to origin and the stop position when stopping by the mechanical stopper.
Note 2. The shaded position indicates an user cable extraction port.

Note 3. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.

Controller
RCX240 ▶ 402