

- Arm type
- Cable carrier
- Z-axis: clamped table / moving base type (200W)

Ordering method

SXYx - C				ZFH			RXC240		R			BB	
Model	Cable	Combination	X-axis stroke	Y-axis stroke	ZR-axis	Z-axis stroke	Cable length	Controller	Usable for CE	Regenerative unit	Option I/O	Network option	Battery
A1 A2 A3 A4			15 to 105cm	15 to 65cm		15 to 35cm	3L: 3.5m (Standard) 5L: 5m 10L: 10m		No entry: Standard E: CE marking	R: RGU-2	N, P: Standard I/O 16/8 N1, P1: 40/24 N2, P2: 64/40 N3, P3: 88/56 N4, P4: 112/72	No entry: None CC: CC-Link DN: DeviceNet PB: Profibus EN: Ethernet YC: YC-Link	BB: 4 pcs

Note 1. N to N4 if NPN was selected, or P to P4 if PNP was selected for the I/O board.
Note 2. Available only for the master.

Specification

	X-axis	Y-axis	Z-axis
Axis construction ^{Note 1}	F14H	F14	F10 equivalent guide-reinforced model
AC servo motor output (W)	200	100	200
Repeatability ^{Note 2} (mm)	+/-0.01	+/-0.01	+/-0.01
Drive system	Ball screw (Class C7)	Ball screw (Class C7)	Ball screw (Class C7)
Ball screw lead (Deceleration ratio) (mm)	20	20	10
Maximum speed ^{Note 3} (mm/sec)	1200	1200	600
Moving range (mm)	150 to 1050	150 to 650	150 to 350
Robot cable length (m)	Standard: 3.5 Option: 5,10		

Note 1. Use caution that the flame machining (installation holes, tap holes) differs from single-axis robots.
Note 2. Positioning repeatability in one direction.
Note 3. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

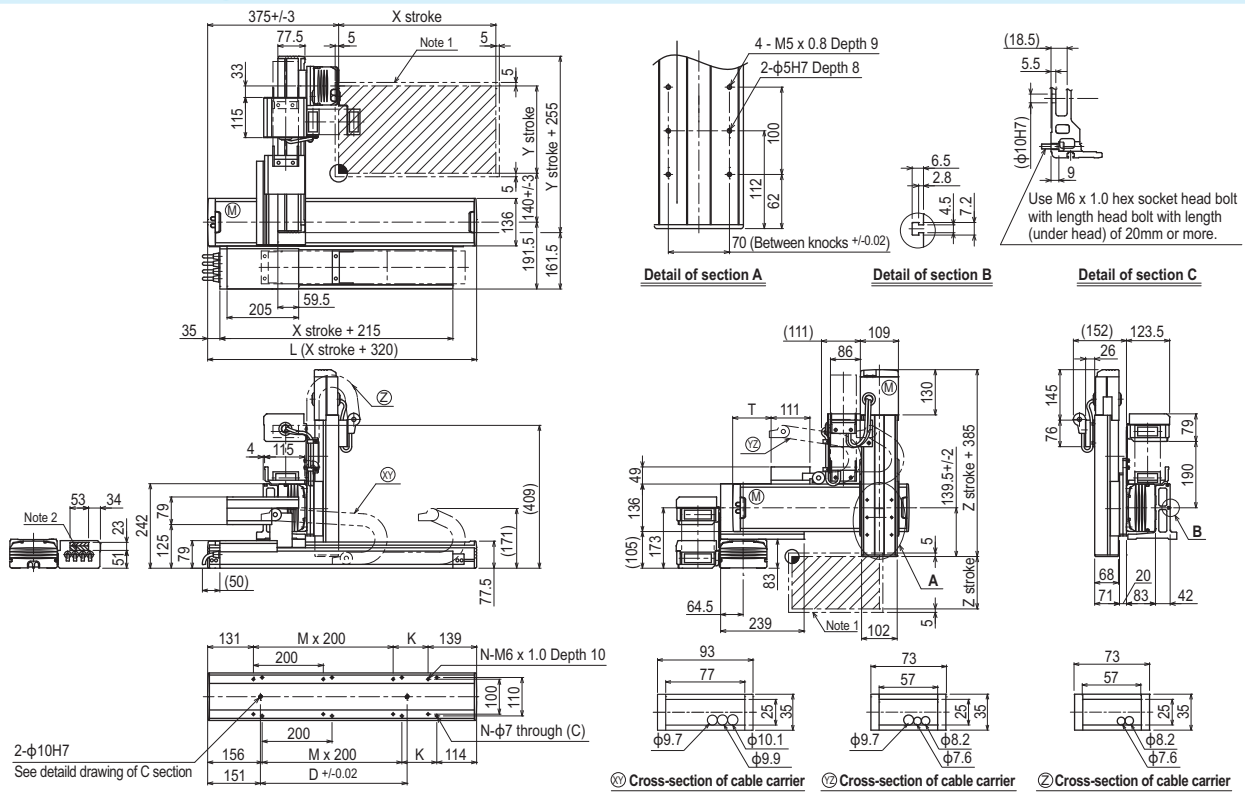
Maximum payload (kg)

Y stroke (mm)	Z stroke (mm)		
	150	250	350
150	13	12	11
250	10	9	8
350	8	7	6
450	6	5	4
550	4	3	2
650	2	1	1

Controller

Controller	Operation method
RXC240-R	Programming / I/O point trace / Remote command / Operation using RS-232C communication

SXYx 3 axes / ZFH (A1)



X stroke	Stroke (mm)										
	150	250	350	450	550	650	750	850	950	1050	
L	470	570	670	770	870	970	1070	1170	1270	1370	
K	200	100	200	100	200	100	200	100	200	100	
D	240	240	420	420	600	600	780	960	960	1140	
M	0	1	1	2	2	3	3	4	4	5	
N	4	6	6	8	8	10	10	12	12	14	
Y stroke	Stroke (mm)										
T	55	110	165	220	275	330					
Z stroke	Stroke (mm)										
	150	250	350								
Maximum speed for each stroke (mm/sec) ^{Note 3}	X-axis		1200			960	780	600	540		
Speed setting			-			80%	65%	50%	45%		

Note 1. The moving range when returning to origin and the stop position when stopping by the mechanical stopper.
Note 2. The shaded position indicates an user cable extraction port.

Note 3. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.

APPLICATION
Compact
single-axis robots
TRANSERO

Single-axis robots
FLIP-X

Linear motor
single-axis robots
PHASER

Cartesian
robots
XX-X

SCARA
robots
YK-XG

Pick & place
robots
YP-X

CLEAN

CONTROLLER
INFORMATION

Arm type

Gantry type

Moving arm
type

Pole type

XZ type