

# S05, S10, S20 Series Spring Return Direct Coupled Actuators

CS4105, CS4110, CS4120, CS7505, CS7510, CS7520, CS8105,  
CS8110, CS8120

## INSTALLATION INSTRUCTIONS

### INSTALLATION

#### When Installing this Product...

1. Read these instructions carefully. Failure to follow them could damage the product or cause a hazardous condition.
2. Check the ratings given in the instructions and on the product to make sure the product is suitable for your application.
3. Installer must be a trained, experienced service technician.
4. After installation is complete, check out product operation as provided in these instructions.

**!** **CAUTION**  
**Electrical Shock or Equipment Damage Hazard.**  
**Low voltage can shock individuals or short equipment circuitry.**  
 Disconnect power supply before installation.

**IMPORTANT**  
*All wiring must agree with applicable codes, ordinances and regulations.*

#### Location

These actuators are designed to mount directly to a damper external drive shaft. The shaft coupling fastens to the drive shaft. The actuator housing includes slots which, along with an anti-rotation bracket, secure the actuator to the damper frame or duct work (see Fig. 8).

#### NOTES:

- When mounted correctly, these slots allow the actuator to *float* without rotating relative to the damper shaft.
- Using other brackets or linkages, the actuator can be foot-mounted or tandem-mounted.

**!** **CAUTION**  
**Motor Damage Hazard.**  
**Deteriorating vapors and acid fumes can damage metal parts.**  
 Install motor in areas free of acid fumes and other deteriorating vapors.

**!** **CAUTION**  
**Equipment Damage Hazard.**  
**Tightly securing actuator to damper housing can damage actuator.**  
 Mount actuator to allow it to float along its vertical axis.

#### Preparation

Before mounting the actuator onto the damper shaft, determine the:

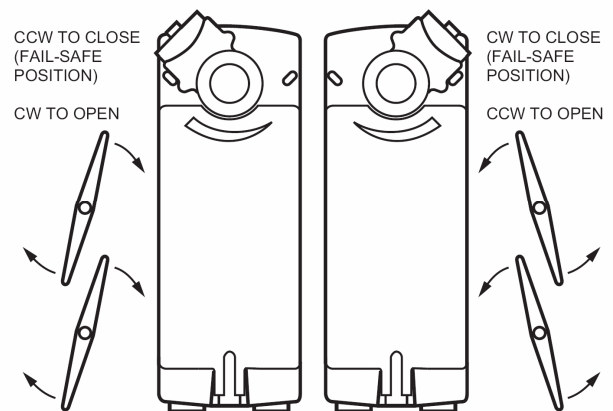
- Damper/valve opening direction for correct spring return rotation. The actuator can be mounted to provide clockwise or counterclockwise spring return.
- Damper shaft size (see the Specifications section).

#### Determine Appropriate Mounting Orientation

The actuators are designed to open a damper by driving the damper shaft in either a clockwise or counterclockwise direction (see Fig. 2).

#### NOTES:

- Actuators are shipped in the fully closed (spring return) position.
- An arrow molded into the hub points to tick marks on the label to indicate the hub rotary position.



**Fig. 2. Spring Return DCA mounting orientation.**

#### Measure Damper/Valve Shaft Length

If the shaft is less than three inches in length, the shaft coupling must be located between the damper/valve and actuator housing. If the shaft length is more than three inches, the shaft coupling may be located on either side of the actuator housing.

If the coupling must be moved from one side of the actuator to the reverse, follow these instructions (see Fig. 3):

1. Remove the retainer clip from the shaft coupling and set it aside for later use.
2. Remove shaft coupling from one side of the actuator.
3. Replace the shaft coupling on the opposite side of the actuator aligning it based on the stroke labeling.
4. Replace the retainer clip on the shaft coupling using the groove of the coupling.

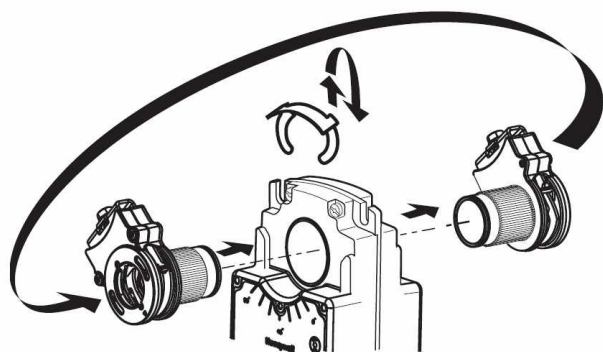


Fig. 3. Mounting shaft coupling to actuator opposite side.

— Enhanced: includes different mode selection dial to select the desired input signal. Also includes dials for adjusting the input signal zero and span.

NOTE: Selections are made using a dial that appears on both the front and back of the actuator (see Fig. 4). For available options, see Table 5.

To select the control signal simply turn the mode selection dial to the desired control signal (as indicated on the device label).

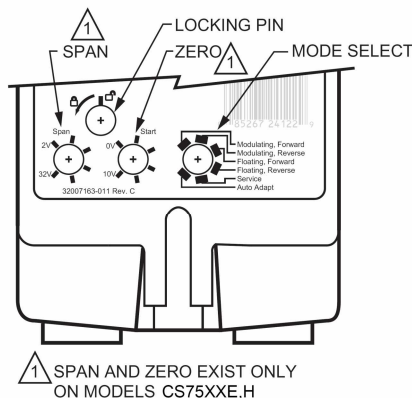


Fig. 4. Dials for control signal and zero/span.

### Select Actuator Control Signal

These actuators are available in two control types:

— Standard: includes mode selection dial to select the desired input signal.

Table 5. Actuator Control Signal Selections.

Mode Options	Standard	Enhanced	Details
Floating: forward	X <sup>a</sup>	X <sup>a</sup>	Power to terminal 4 drives toward spring return position.
Floating: reverse	X <sup>b</sup>	X <sup>b</sup>	Power to terminal 3 drives toward spring return position.
Modulating: 0-10 VDC	X <sup>c</sup>		0 VDC signal drives toward spring return position.
Modulating: 10-0 VDC	X <sup>c</sup>		10 VDC signal drives toward spring return position.
Modulating: 2-10 VDC	X <sup>c</sup>		2 VDC signal drives toward spring return position.
Modulating: 10-2 VDC	X <sup>c</sup>		10 VDC signal drives toward spring return position.
Modulating: forward		X	Voltage input with adjustable zero and span. Minimum signal drives toward spring return position.
Modulating: reverse		X	Voltage input with adjustable zero and span. Maximum signal drives toward spring return position.
Service		X	Actuator hub stops in place and ignores control signal changes.
Auto-adapt		X	For setup only. Rescales to allow full input signal over mechanically limited stroke.

<sup>a</sup> Feedback: CS75XXA,H and U.S. S... models are 2-10 VDC, CS75XXB,E and European S... models are 0-10 VDC.

<sup>b</sup> Feedback: CS75XXA,H and U.S. S... models are 10-2 VDC, CS75XXB,E and European S... models are 10-0 VDC

<sup>c</sup> When operating in Modulating mode, the feedback signal matches the control signal.

### Non-Standard Stroke

#### Mechanical Stroke Limit Reduction

For applications requiring a span less than 95 degrees, a simple adjustment can be made. When the rotational mounting of the shaft coupling is changed, the actuator drives less than the full 95 degrees stroke.

The stroke is adjustable in 5 degree increments. Once adjusted, the actuator drives until the shaft coupling reaches the mechanical stop (part of the housing). The stop causes the motor to discontinue driving and the shaft coupling drives no farther. When the actuator returns, it stops at the fail-safe position.

To set the fail-safe position, proceed as follows:

1. Remove the retainer clip from the shaft coupling and set it aside for later use.
2. Remove shaft coupling from the actuator.
3. Rotate the coupling to the desired fail-safe position, aligning it based on the stroke labeling. See Fig. 5.

NOTE: The shaft coupling location determines the travel span.

EXAMPLE: Setting shaft coupling to an approximate fail-safe position of 35 degrees (as indicated on the housing) limits stroke to 60 degrees. (See Fig. 5)

4. Install the shaft coupling at this position.
5. Replace the retainer clip on the shaft coupling using the groove of the coupling.
6. If necessary, replace the holder and position indicator on the shaft coupling.

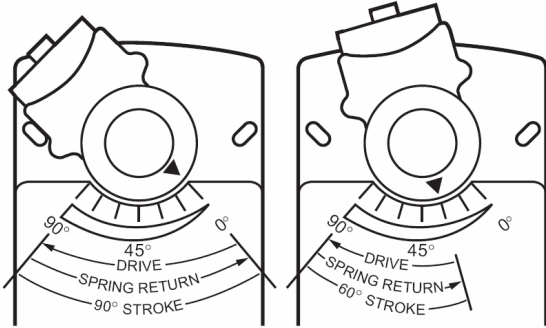


Fig. 5. Stroke reduction.

### Adjustable Zero and Span (Enhanced Modulating Models *only*)

These actuators have the capability of adjustable Zero and Span. Fig. 4 shows the dials. These dials are present only on the Enhanced Modulating models. A basic description of these dials follows:

- Zero: Sets input voltage to define the 0% angle of rotation. It is factory set to 0 VDC, and can be adjusted up to 10 VDC.
- Span: Adjusts motor response to travel full stroke through the selected input span. It is factory set to 10 VDC, and is adjustable from 2 to 32 VDC.

#### SET ADJUSTABLE ZERO AND SPAN

1. Apply 24 VAC/VDC to the actuator.
2. Turn the Zero dial (see Fig. 4) past the desired start point.
3. Using either a controller or signal generator, apply an input signal equal to the start point signal.

4. Slowly adjust Zero toward the minimum setting until the actuator hub begins to move.
5. Turn the Span dial (see Fig. 4) to the minimum setting (2 VDC).
6. Using either a controller or signal generator, apply an input signal equal to the desired end point signal.
7. Allow the actuator to open fully.
8. Slowly adjust Span toward the maximum setting until the actuator hub moves slightly from fully open.
9. Carefully adjust Span knob toward minimum until the actuator hub returns to fully open.

#### Auto-Adapt

When using these actuators for standard stroke applications, this function can be ignored. When it is desirable to use a mechanically limited stroke (see Mechanical Stroke Limit Reduction section), it is possible to use the Auto-Adapt feature to rescale the input signal over the new limited stroke.

1. Rotate actuator control signal dial to Auto-Adapt.

NOTE: The actuator will drive open, then closed to establish the new open and closed positions.

2. Return the actuator control signal dial to the desired input signal position.

### Manual Positioning

The actuator can be operated with no power present. Use this feature during installation or to move and lock the damper or valve shaft position when there is no power.

To operate the manual positioning:

1. If the power is on, turn it off.
2. Insert supplied hex wrench (key) as shown in Fig. 6.
3. Rotate key in the direction indicated on the cover.
4. Once the desired position is reached, hold the key to prevent the spring return from moving the actuator.
5. With the key held in place, use a screwdriver to turn the gear train lock pin in the indicated direction until the detent is reached.

NOTE: At the detent, the pin resists further rotation.

6. Remove the key without rotating it further.

To release the manual positioning with no power present:

1. Insert supplied key.
2. Turn key 1/4 turn in the direction indicated on the cover.
3. Remove key without engaging the gear train lock pin.
4. The spring will return actuator to the fail-safe position.

NOTE: Once power is restored, the actuator will return to normal automated control.

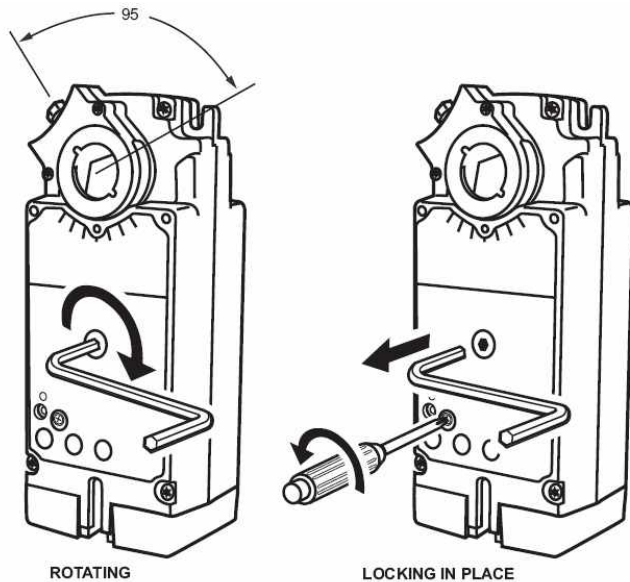


Fig. 6. Manual positioning.

- Using 10 mm wrench, tighten shaft coupling securely onto damper shaft using minimum 120 lb-in. (13.6 N•m), maximum 180 lb-in. (20.3 N•m) torque.

NOTE: See Fig. 7 for proper mounting to a square damper shaft.

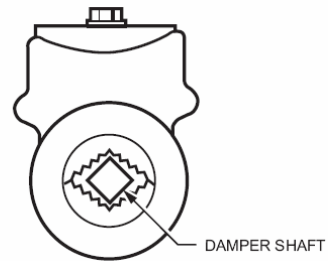


Fig. 7. Proper mounting to square damper shaft.

## Mounting

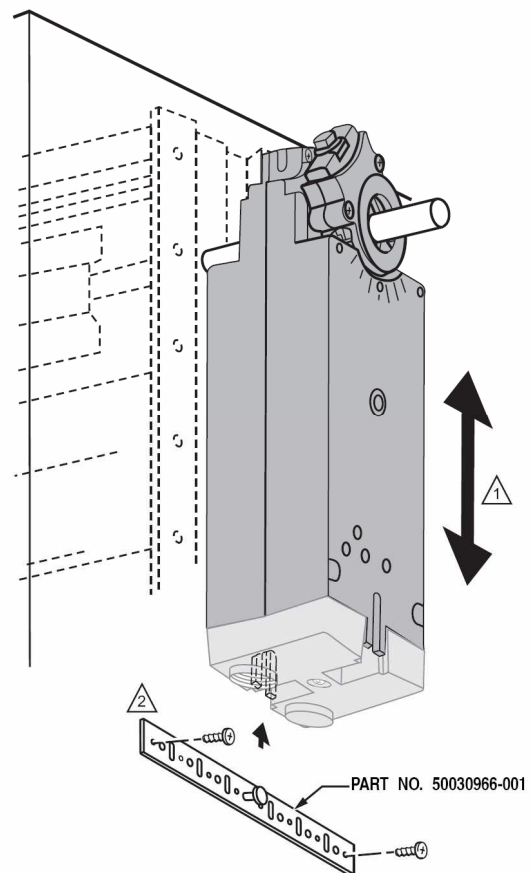
**CAUTION**  
**Device Malfunction Hazard.**  
 Improper shaft coupling tightening causes device malfunction.  
 Tighten shaft coupling with proper torque to prevent damper shaft slippage.

**CAUTION**  
**Actuator Damage Hazard.**  
 Using actuator as shaft bearing causes device damage.  
 Use actuator only to supply rotational torque. Avoid any side loads to actuator output coupling bearings.

**CAUTION**  
**Equipment Damage Hazard.**  
 Can damage the motor beyond repair.  
 Never turn the motor shaft by hand or with a wrench. Forcibly turning the motor shaft can damage the gear train.

To mount the actuator to an external drive shaft of a damper, proceed as follows:

- Place actuator over damper shaft; and hold mounting bracket in place. See Fig. 8.
- Mark screw holes on damper housing.
- Remove actuator and mounting bracket.
- Drill or center-punch holes for mounting screws (or use no.10 self-tapping sheet metal screws).
- Turn damper blades to desired normal (closed) position.
- Place actuator and mounting bracket back into position and secure bracket to damper box with sheet metal screws.



⚠️ ENSURE THAT MOUNTING ASSEMBLY PREVENTS ACTUATOR ROTATION AND ALLOWS ACTUATOR TO FLOAT ALONG INDICATED AXIS. WHEN TOO TIGHT, THE RESULTING BINDING CAN DAMAGE THE ACTUATOR OR REDUCE TORQUE OUTPUT.

⚠️ THE BRACKET CAN BE BENT TO ALLOW MOUNTING THE ACTUATOR PARALLEL TO THE MOUNTING SURFACE.

Fig. 8. Mounting actuator to damper housing.

## WIRING



### CAUTION

**Electrical Shock or Equipment Damage Hazard.**  
**Disconnect all power supplies before installation.**  
 Motors with auxiliary switches can have more than one disconnect.

#### IMPORTANT

*All wiring must comply with local electrical codes, ordinances and regulations.*

### Access Cover Removal (Fig. 9)



### CAUTION

**Equipment Damage Hazard.**  
**Improper cover removal can damage electric connections.**  
 Pull the cover along the axis of the actuator.  
 The cover contains contact sockets that must connect to actuator contact pins.  
 Bending these pins can permanently damage the device.

NOTE: This cover can be removed before or after actuator mounting.

In order to wire the device, the access cover must be removed as follows:

1. Remove the screw from the center of the cover, set the screw aside.
2. Pull the cover along the long axis of the actuator.
3. If the actuator is not yet mounted, set it aside.
4. Remove conduit dust covers as necessary.
5. Thread wire through conduit holes.
6. Connect wires as appropriate to the terminal block(s). (See Fig. 10 and 11.)

NOTE: With US Models, use 1/2 in. NPS strain relief gland or 1/2 in. conduit adapters. Recommend using flex conduit.  
 With European Models, use M16 strain relief gland.

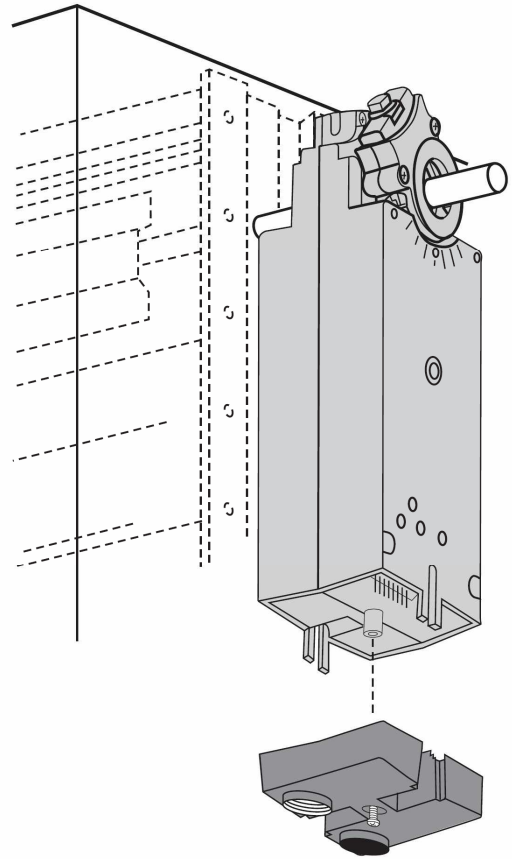


Fig. 9. Removing access cover.

### Typical Wiring

See Fig. 10 through 26 for typical wiring details.

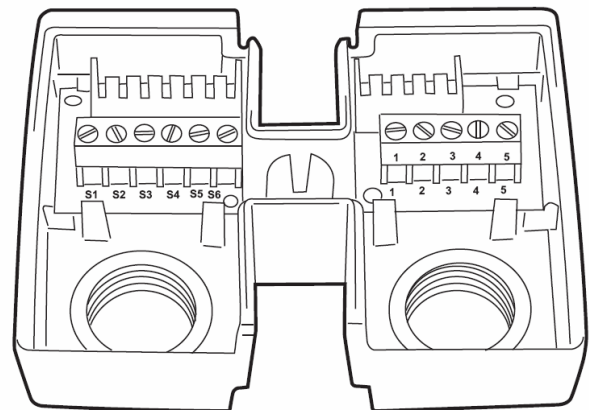
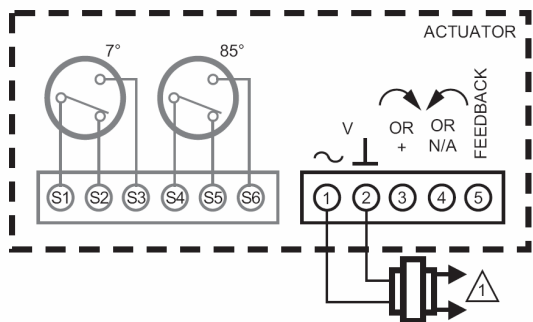


Fig. 10. Terminal block details.



1 POWER SUPPLY. PROVIDE DISCONNECT MEANS AND OVERLOAD PROTECTION AS REQUIRED.

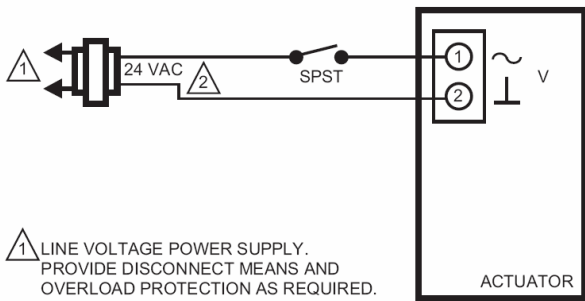
Fig. 11. Terminal block details.

Table 6. Wiring details.

Terminal	Floating	Modulating	Two-Position		Color <sup>a</sup>
			24 VAC/ VDC	100-250 VAC	
~ 1	power	power	power	power	Red
⊥ 2	common	common	common	neutral	Black
↻→ 3	cw	input	—	—	White
↻↺ 4	ccw	—	—	—	—
← 5	feedback	feedback	—	—	Brown

<sup>a</sup> Only applies to models with wires.

Sxx24-2POS Models

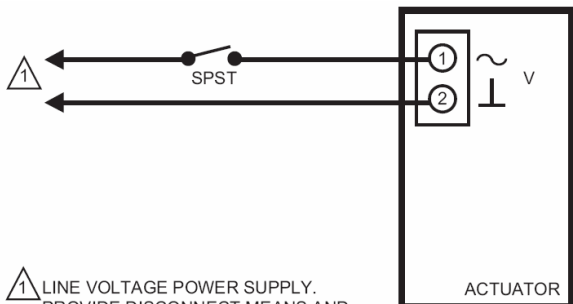


1 LINE VOLTAGE POWER SUPPLY. PROVIDE DISCONNECT MEANS AND OVERLOAD PROTECTION AS REQUIRED.

2 24 VDC SUPPLY ACCEPTABLE.

Fig. 12. Wiring for low-voltage two-position control.

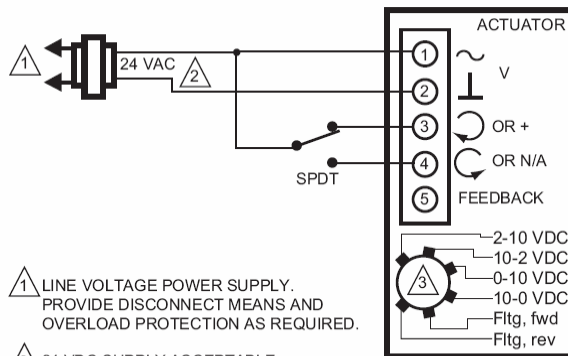
Sxx120-2POS, Sxx230-2POS Models



1 LINE VOLTAGE POWER SUPPLY. PROVIDE DISCONNECT MEANS AND OVERLOAD PROTECTION AS REQUIRED.

Fig. 13. Wiring for line-voltage two-position control.

Sxx010 Models

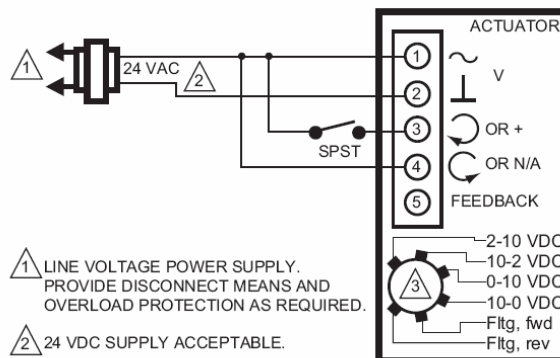


1 LINE VOLTAGE POWER SUPPLY. PROVIDE DISCONNECT MEANS AND OVERLOAD PROTECTION AS REQUIRED.

2 24 VDC SUPPLY ACCEPTABLE.

3 SET SWITCH TO FLOATING.

Fig. 14. Wiring for SPDT on/off control.

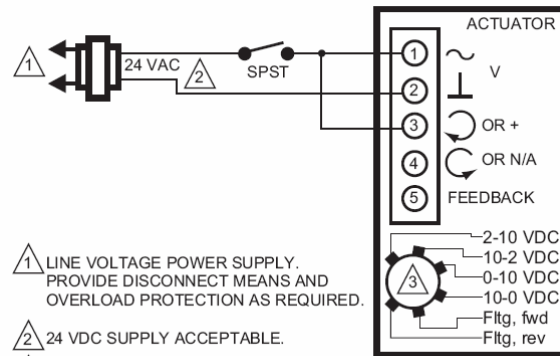


1 LINE VOLTAGE POWER SUPPLY. PROVIDE DISCONNECT MEANS AND OVERLOAD PROTECTION AS REQUIRED.

2 24 VDC SUPPLY ACCEPTABLE.

3 SET SWITCH TO FLOATING.

Fig. 15. Wiring for SPST on/off control.



1 LINE VOLTAGE POWER SUPPLY. PROVIDE DISCONNECT MEANS AND OVERLOAD PROTECTION AS REQUIRED.

2 24 VDC SUPPLY ACCEPTABLE.

3 SET SWITCH TO MODULATING.

Fig. 16. Wiring for two-wire SPST on/off control.

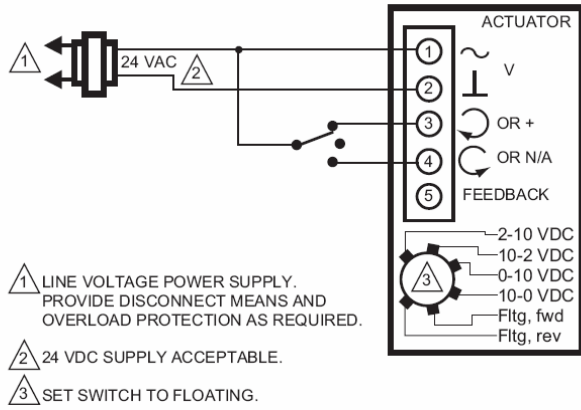


Fig. 17. Wiring for floating control.

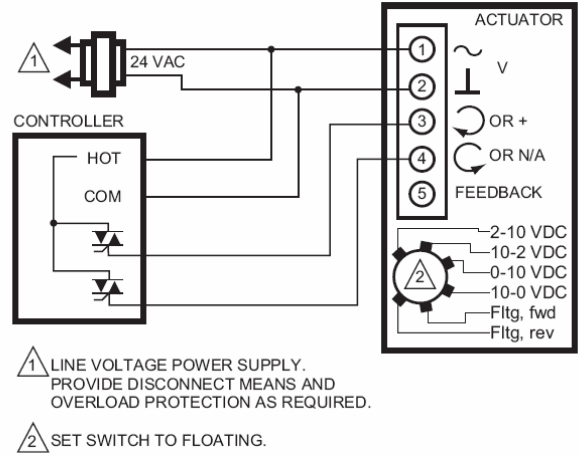


Fig. 20. Wiring for high side (triac source) floating control.

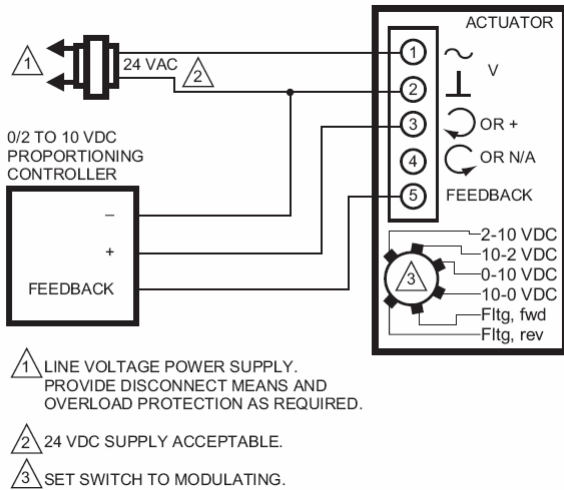


Fig. 18. Wiring for 0/2-10 VDC proportioning controllers.

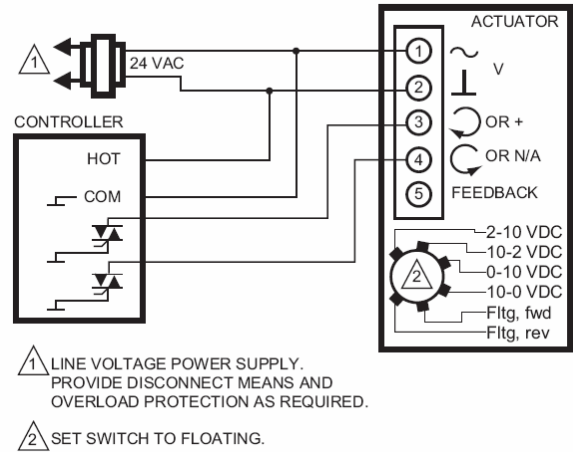


Fig. 21. Wiring for low side (triac sink) floating control.

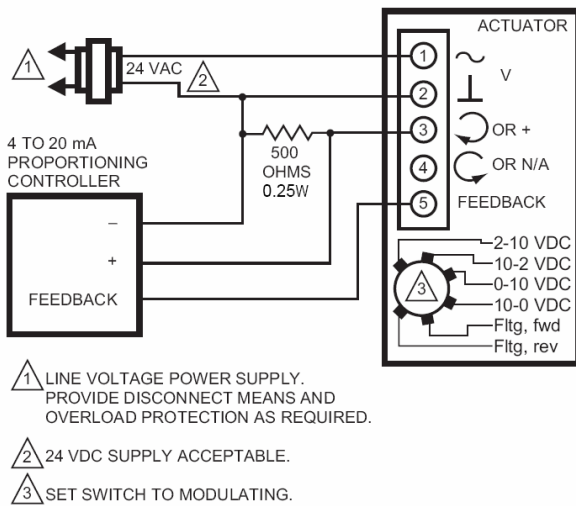


Fig. 19. Wiring for 4-20 mA, proportioning controllers.

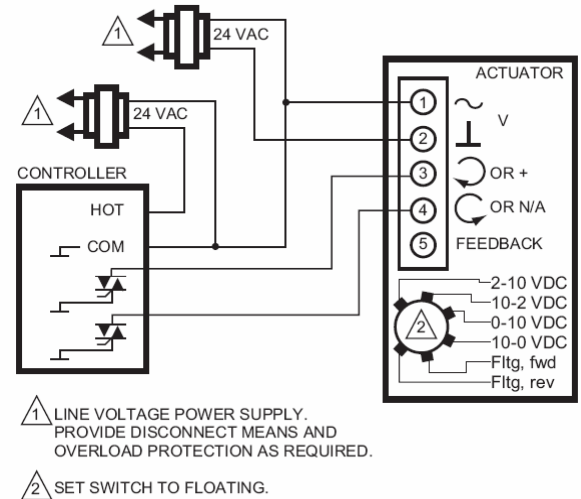


Fig. 22. Wiring for low side (triac sink) floating control using separate transformers.

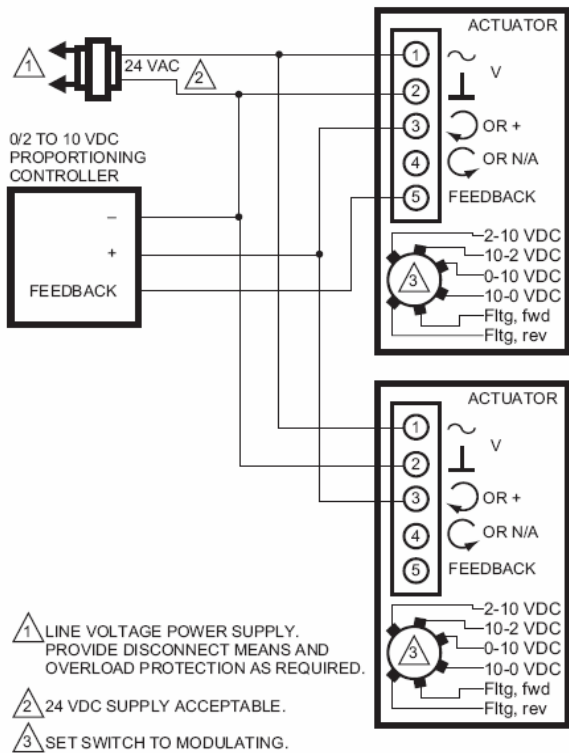


Fig. 23. Wiring for 0/2-10 VDC proportioning controller operating multiple actuators.

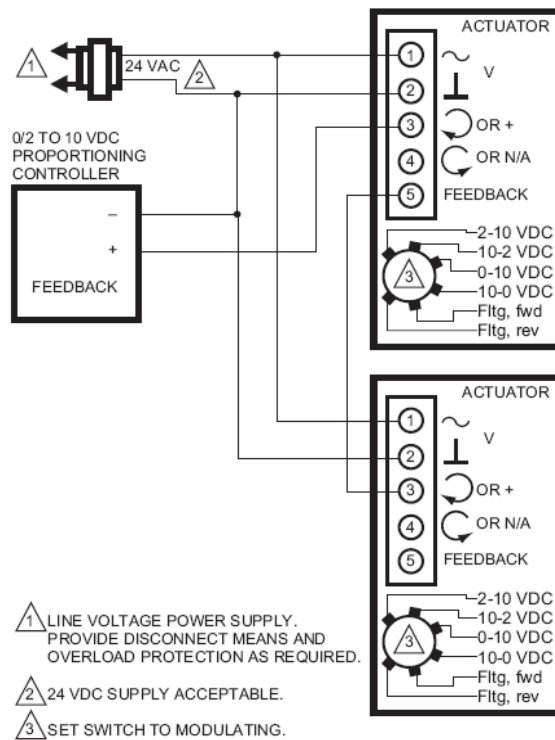


Fig. 25. Wiring for 0/2-10 VDC proportioning controller operating multiple actuators as master/drone.

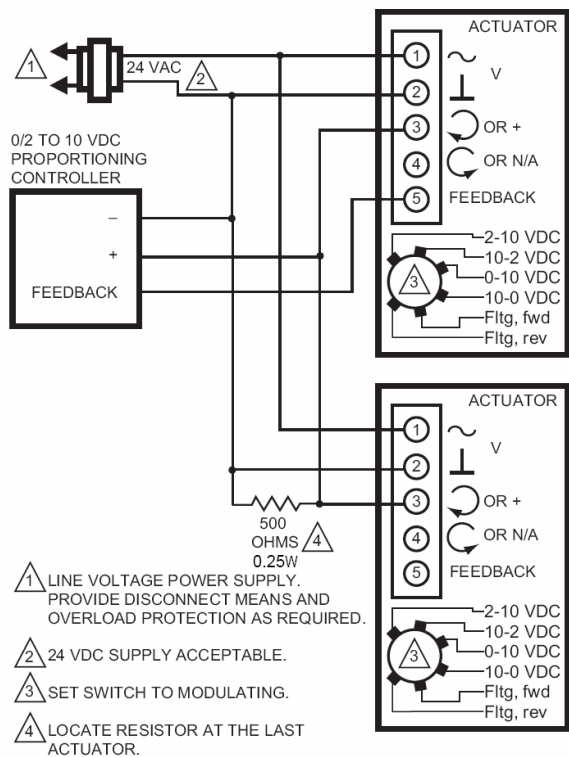


Fig. 24. Wiring for 4-20 mA, proportioning controller operating multiple actuators.

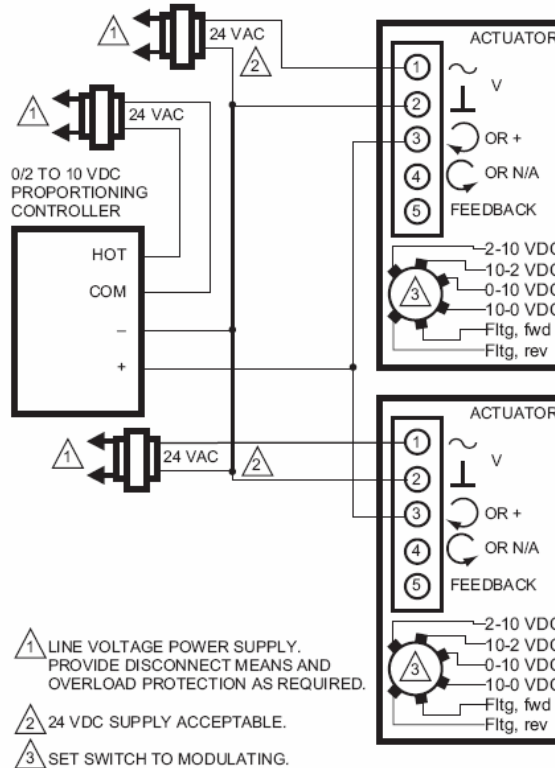


Fig. 26. Wiring for 0/2-10 VDC proportioning controller operating multiple actuators with separate transformers.



## OPERATION

The actuator is designed to be used in ventilating and air conditioning installations to operate valves, dampers, ventilation flaps and louvers requiring torque up to the rating. (For ratings, see the Specifications section.) If the power fails, the actuator will spring return to the start position.

The actuator is operated by a proportional controller. When using a proportional controller, the actuator drives toward its fully open position when the input signal increases; the actuator drives toward the fully closed position when the input signal decreases. The actuator stops when the input signal reaches the desired proportional control point.

### IMPORTANT

*The actuator is designed to respond to DDC Controller instantaneous contact closures. Take care not to short cycle the actuator. Unstable damper control can cause premature actuator failure.*

## Actuator Override

To override the control signal (for freeze protection or similar applications):

1. Override to full open:
  - a. Disconnect the input signal (from terminal 3).
  - b. Apply 24 VAC to terminal 3.
  - c. See Fig. 27.
2. Override to full closed:
  - a. Disconnect the input signal (from terminal 3).
  - b. See Fig. 28.

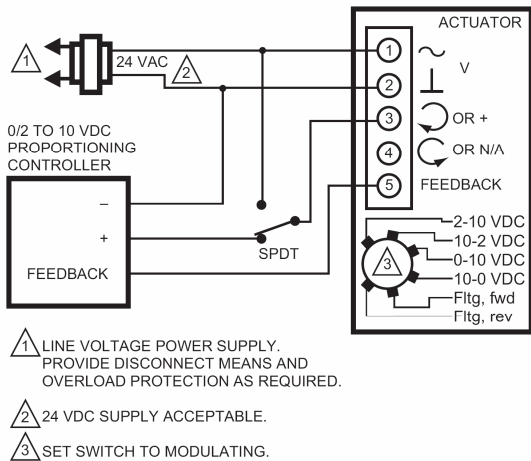


Fig. 27. Override to full open.

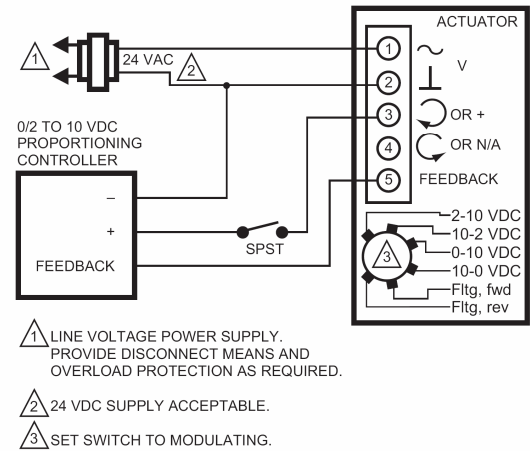


Fig. 28. Override to full close.

## End Switches

Some models include end switches (see Table 2). For wiring details, see Fig. 11.

### SPDT Switches (Fig. 29)

For SPDT end switch wiring, see Fig. 11.

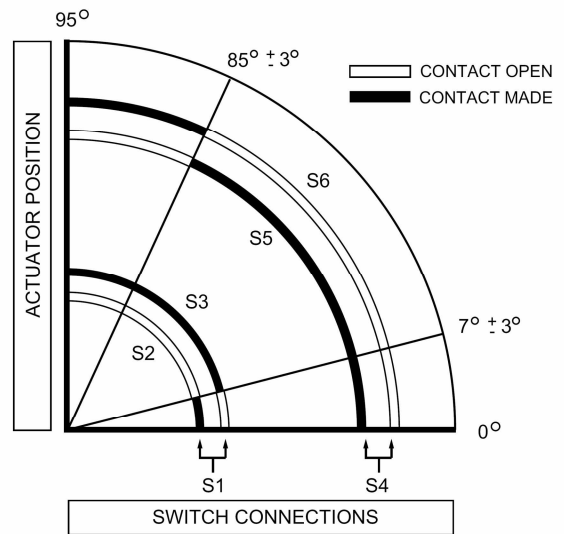






Fig. 29. SPDT End Switch Operation.

## CHECKOUT

### Modulating/Floating Operation

1. Mount actuator for required application (either clockwise  or counterclockwise  rotation to open the damper).
2. Connect power to terminals 1 and 2. (See Fig. 11 and Table 6.)
3. Set "Mode Select" dial to desired control signal. (See Fig. 4 and Table 5.)
4. Apply control signal for actuator 100% position. (See Fig. 11 and Table 6.)
  - a. (0)2-10 VDC: apply 10 VDC signal to terminal 3.
  - b. 10-(0)2 VDC: apply (0)2 VDC signal to terminal 3.
  - c. (0)4-20 mA: apply 20 mA signal to terminal 3.
  - d. 20-(0)4mA: apply (0)4 mA signal to terminal 3.
  - e. Floating: apply 24 VAC/VDC to appropriate CW (3) or CCW (4) terminal.
5. Actuator drives to 100% position.
6. Apply control signal for actuator 0% position. (See Fig. 11 and Table 6.)
  - a. (0)2-10 VDC: apply (0)2 VDC signal to terminal 3.
  - b. 10-(0)2 VDC: apply 10 VDC signal to terminal 3.
  - c. (0)4-20 mA: apply (0)4 mA signal to terminal 3.
  - d. 20-(0)4mA: apply 20 mA signal to terminal 3.
  - e. Floating: apply 24 VAC/VDC to appropriate CW (3) or CCW (4) terminal.
7. Actuator drives to 0% position.

### Spring Return Operation

1. Mount actuator for required application (either clockwise  or counterclockwise  rotation to open the damper).
2. Connect power to terminals 1 and 2. (See Fig. 11 and Table 6.)

NOTE: For two-position models skip to step 5.





3. Set "Mode Select" dial to desired control signal. (See Fig. 4 and Table 5.)
4. Apply control signal for actuator 50% position. (See Fig. 11 and Table 6.)
  - a. DC Input Signal: apply 5-6 VDC signal to terminal 3.
  - b. mA Input Signal: apply 10-12 mA signal to terminal 3.

- c. Floating: apply 24 VAC/VDC to appropriate CW (3) or CCW (4) terminal.
5. Allow the actuator to drive to 50% position.
6. Disconnect wire from terminal 1.
7. Actuator spring returns to 0% position.
8. Re-connect wire to terminal 1, actuator drives towards 100% position.



### Feedback Operation

1. Connect a multi-meter, set for VDC, to terminals 2 and 5.
2. Apply the same signal as in step 4 of Modulating Operation.
3. The multi-meter reading increases to match the input signal as actuator drives towards 100% position.
4. Apply the same signal as in step 6 of Modulating Operation.
5. The multi-meter reading decreases to match the input signal as actuator drives towards 0% position.

### Direct Checkout

1. Mount actuator for required application (either clockwise  or counterclockwise  rotation to open the damper).
2. Check damper position and make sure that 24 VAC/VDC is present at the appropriate connections. (See Fig. 10.)
3. Apply control signal to the appropriate connections to move the damper to the opposite position. The actuator should drive the damper.
4. If actuator does not run, verify that the actuator is properly installed for either clockwise  or counterclockwise  rotation.
5. If actuator is correctly installed and still does not run, replace the actuator.

### Two-Position Checkout

1. Mount actuator for required application (either clockwise  or counterclockwise  rotation to open the damper).
2. Check damper position and make sure that power is present at terminals 1 and 2.
3. Actuator drives to 100% position.
4. Disconnect power from terminals 1 and 2.
5. Actuator spring-returns to 0% position.
6. If actuator is correctly installed and does not run, replace the actuator.



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